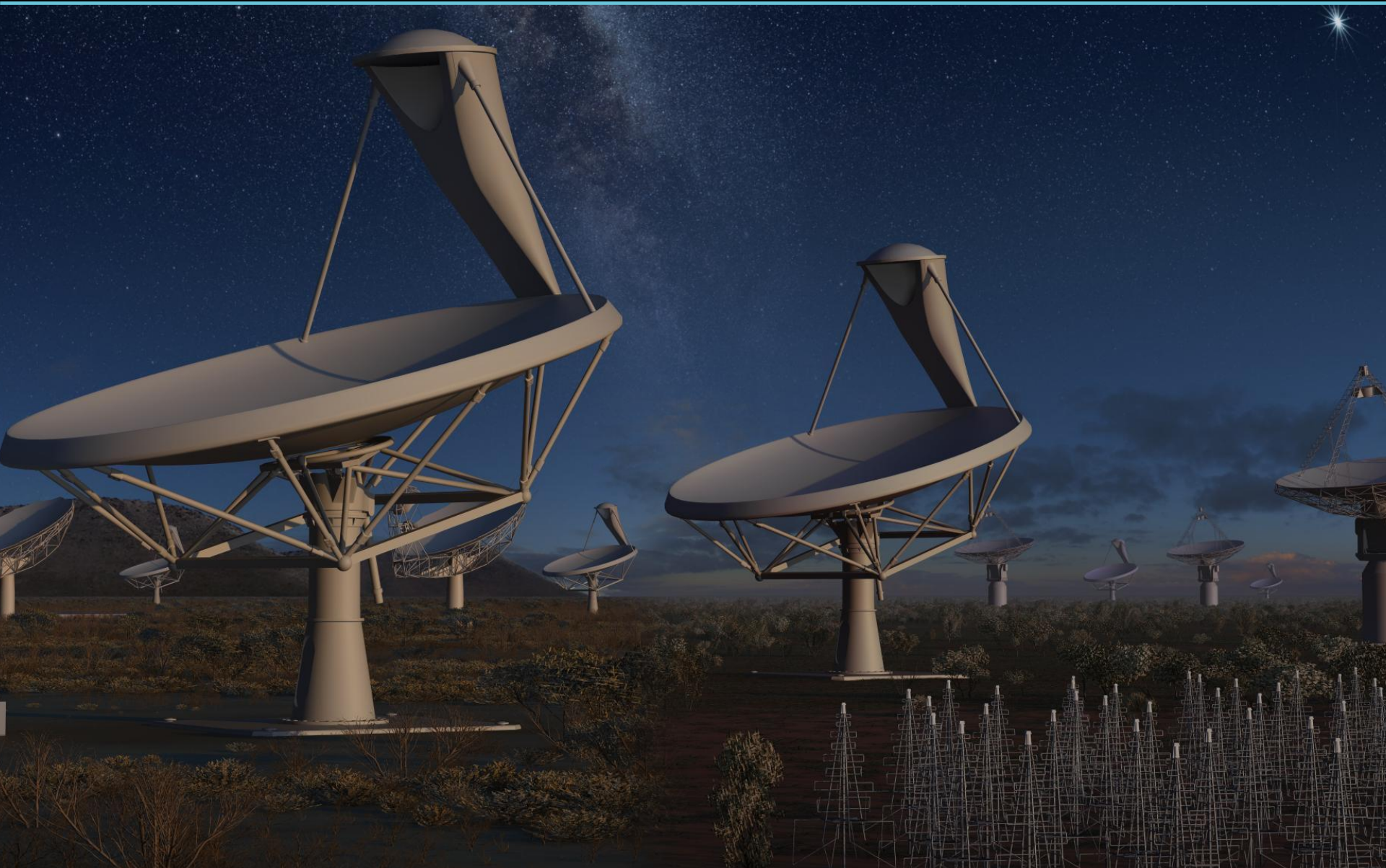
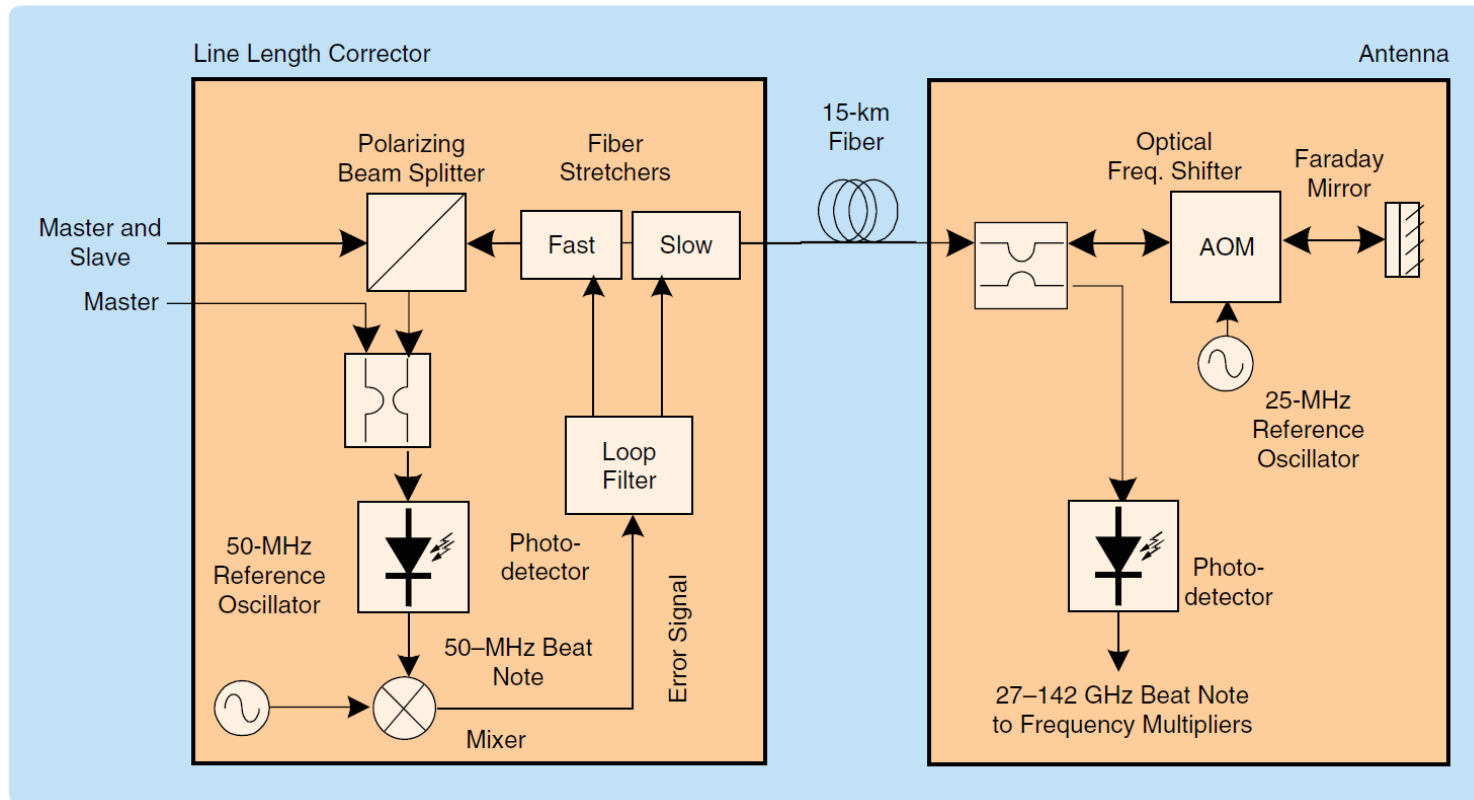


Stabilized frequency transfer for the SKA



Phase coherence for antenna arrays

- Round trip phase measurement — e-MERLIN, ATCA, JVL
- Active phase compensation — DSN, ALMA, SKA

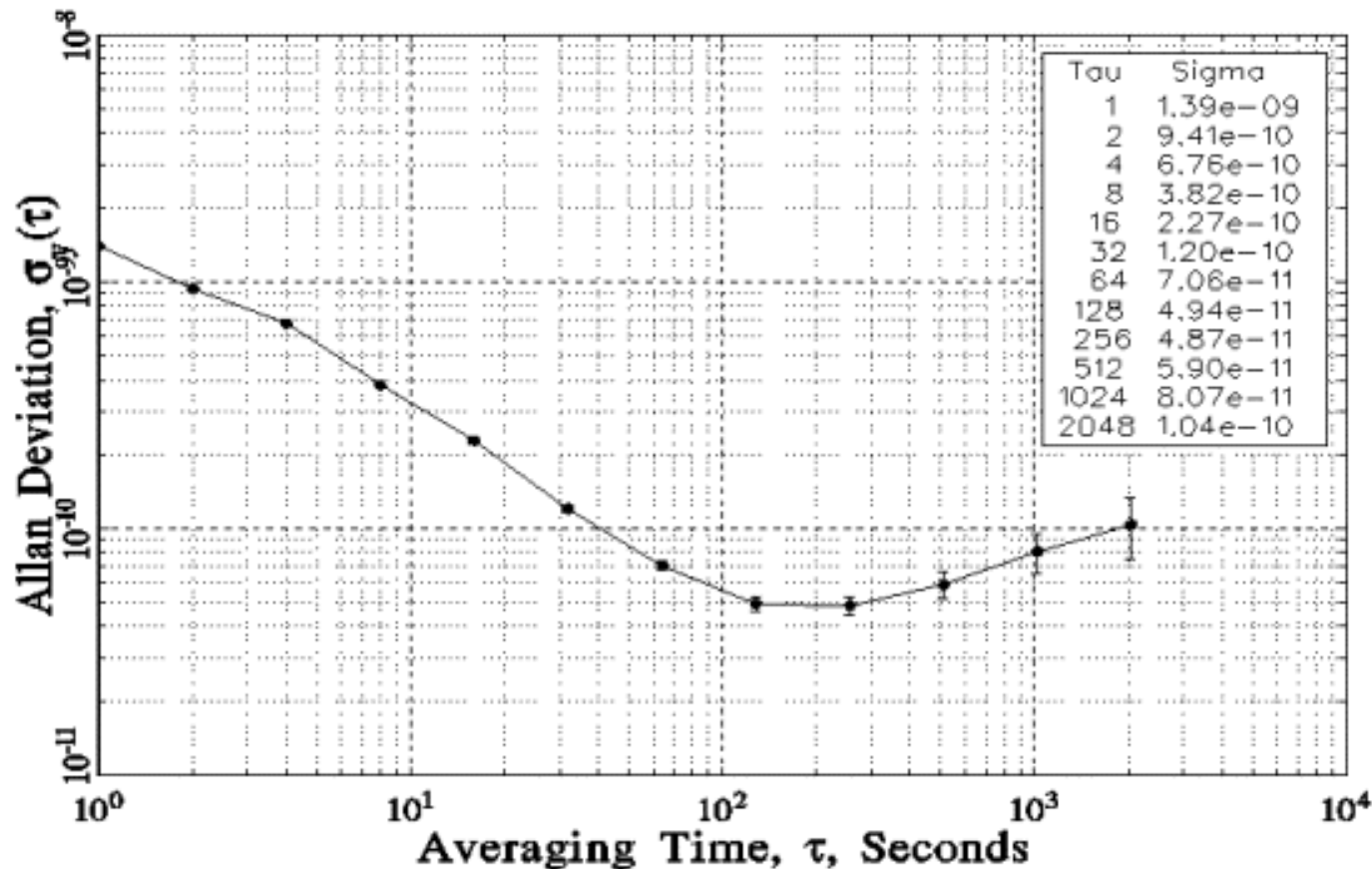


SKA stability requirements

- REQ-2268: max 1 sec coherence loss = 0.2 rad
→ Adev: 2.31×10^{-12} over 1 sec
- REQ-2692: max 60 sec coherence loss = 0.2 rad
→ Adev: 3.84×10^{-14} over 60 sec
- REQ-2693: max phase drift < 1 rad over 10 min
- Link length — up to 173 km
- Other reqs — cost, scalability, glass-box, RFI, etc

Allan deviation

- From Allan (two-sample) variance
- Measure of frequency stability of oscillators

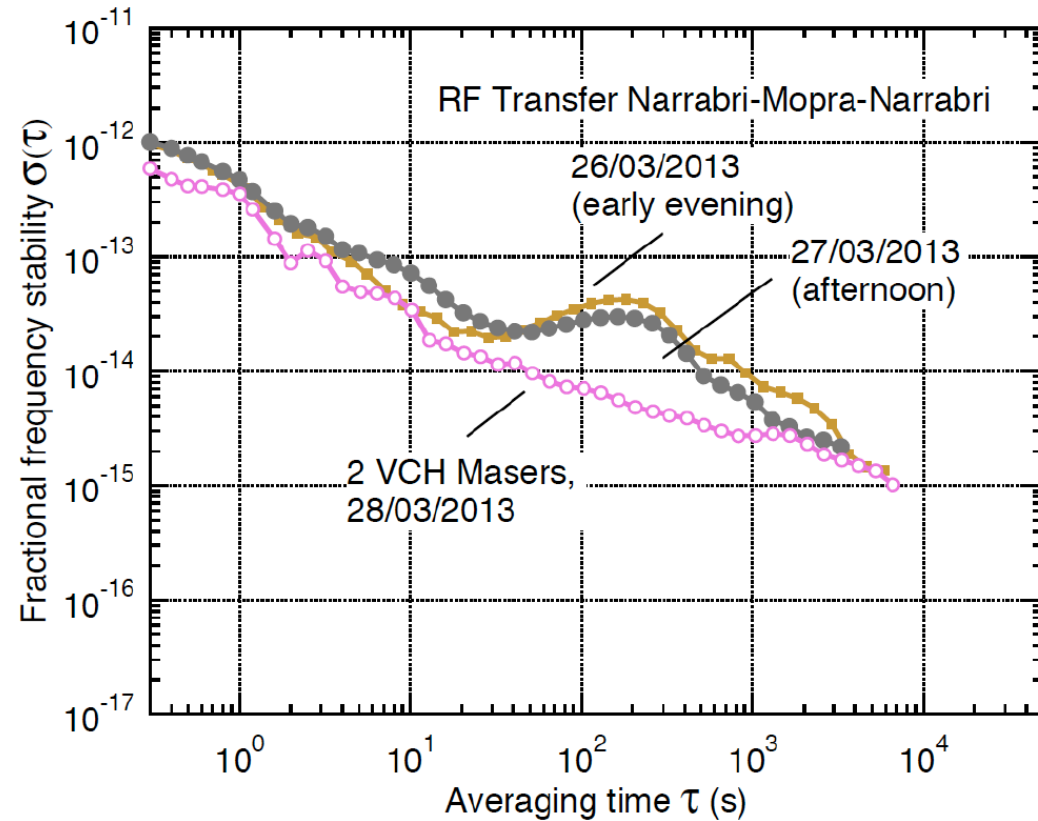
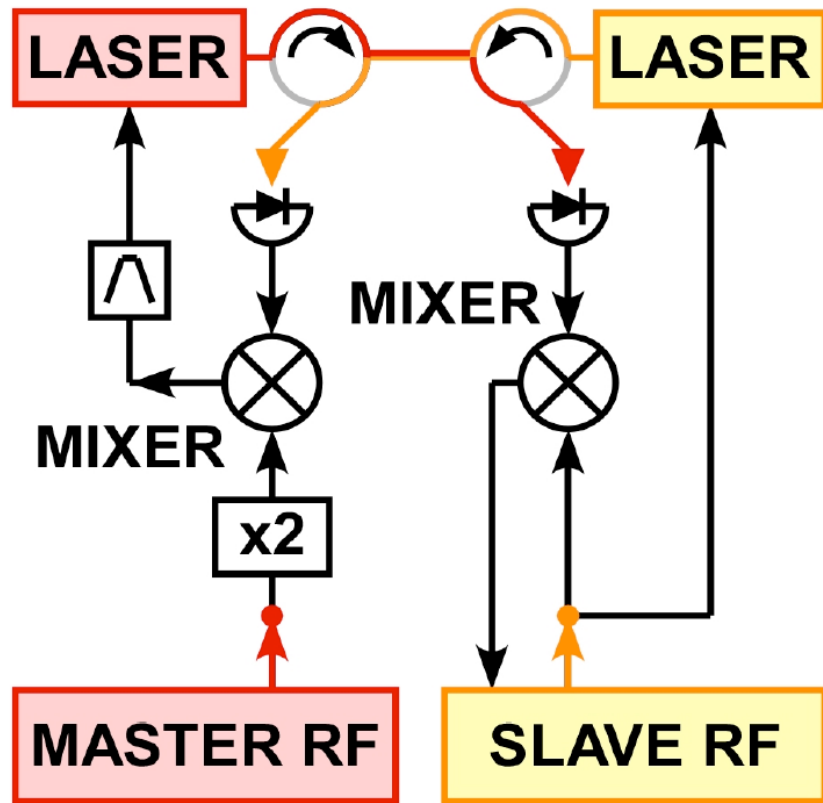


Other SKA.STFR concepts

- University of Manchester — upgraded e-Merlin
- PC — passive, phase conjugation technique
- Tsinghua University (THU) — client-side 1f-2f technique
- UWA — optically-sensed RF/MW transmission

Other concepts — PC

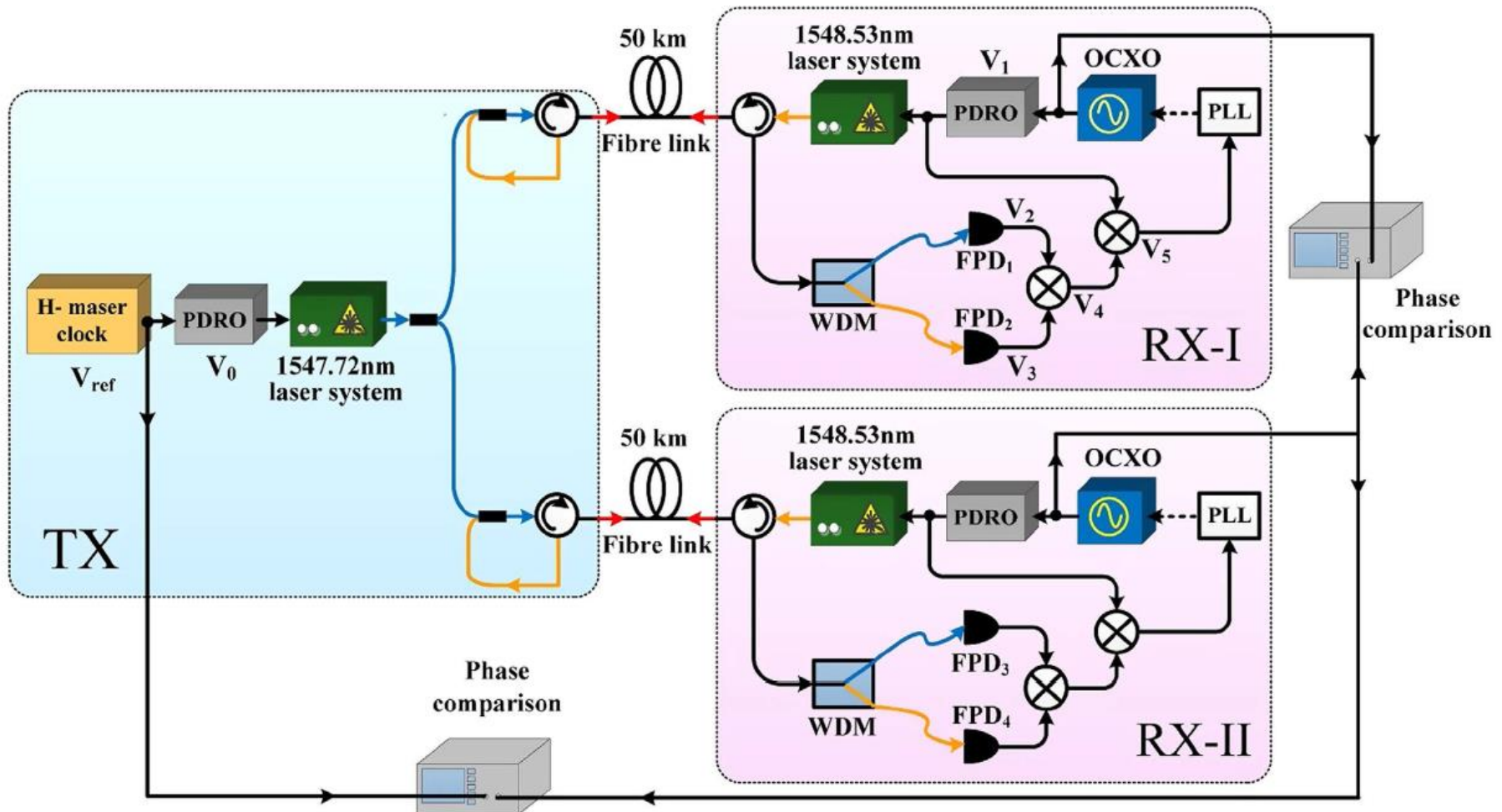
- 310 km link, Mopra-Narrabri-Mopra



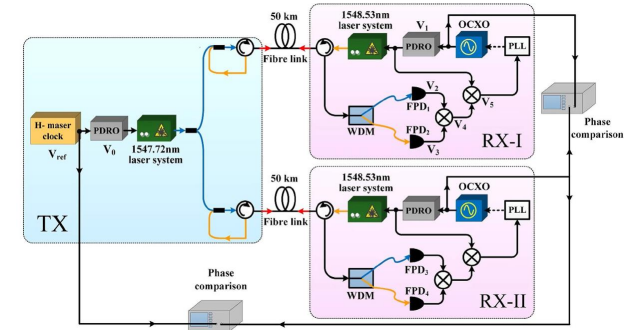
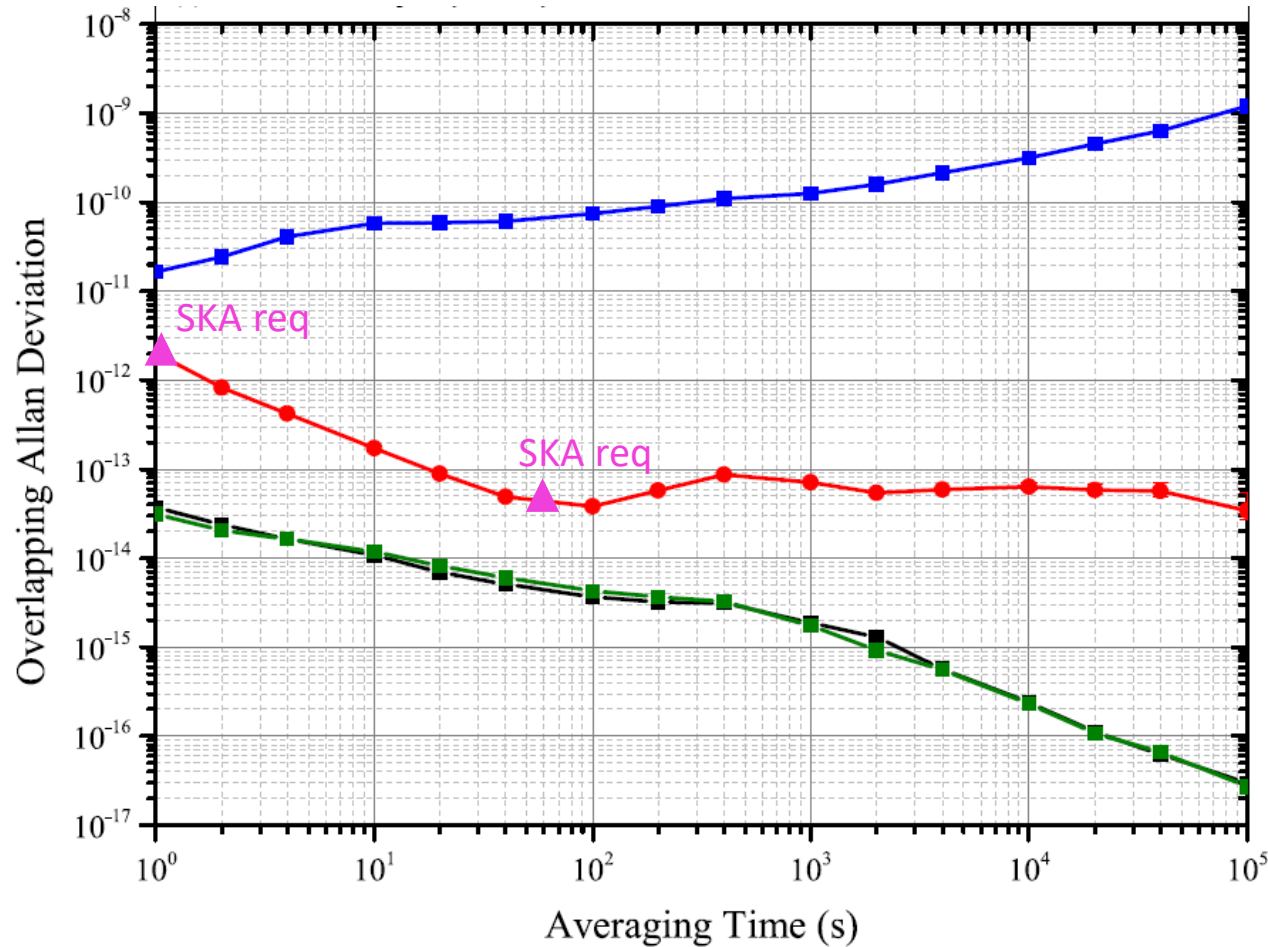
(Baldwin et al. *Phot. Fiber Tech. Congress* 2016)

Other concepts — THU

■ Tsinghua University



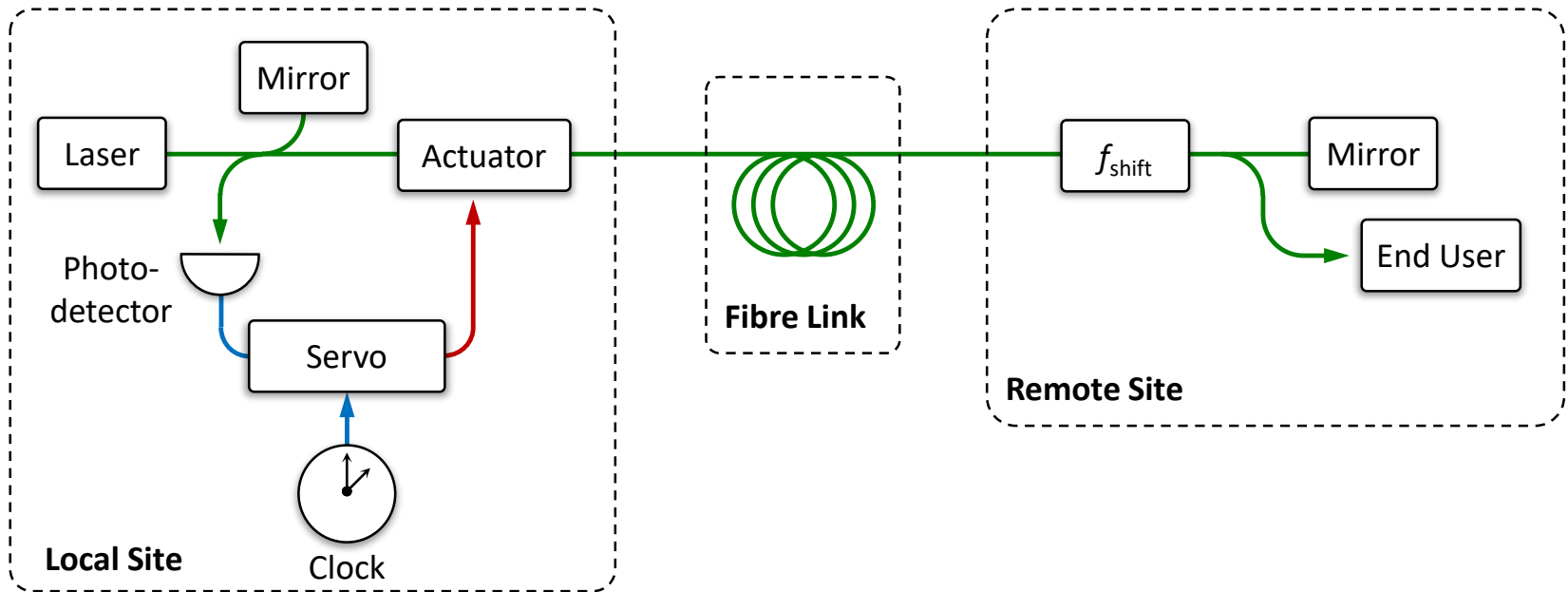
■ Tsinghua University



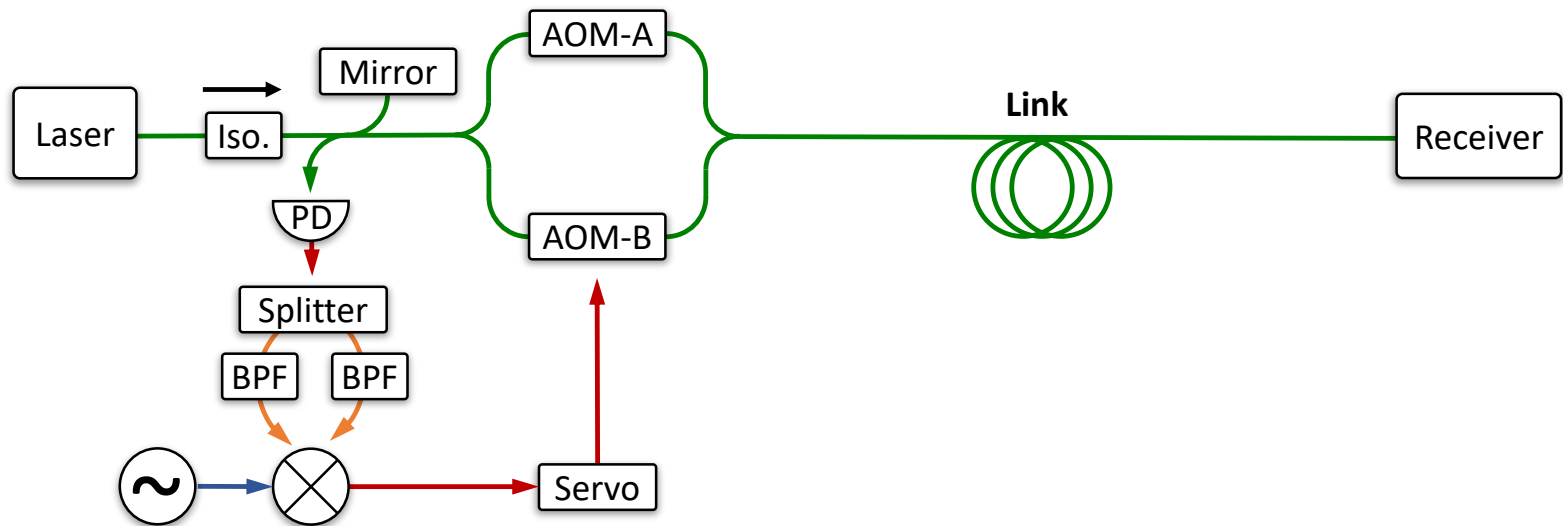
(Wang et al. *Sci. Reports* 2015)

UWA SKA.STFR Concept

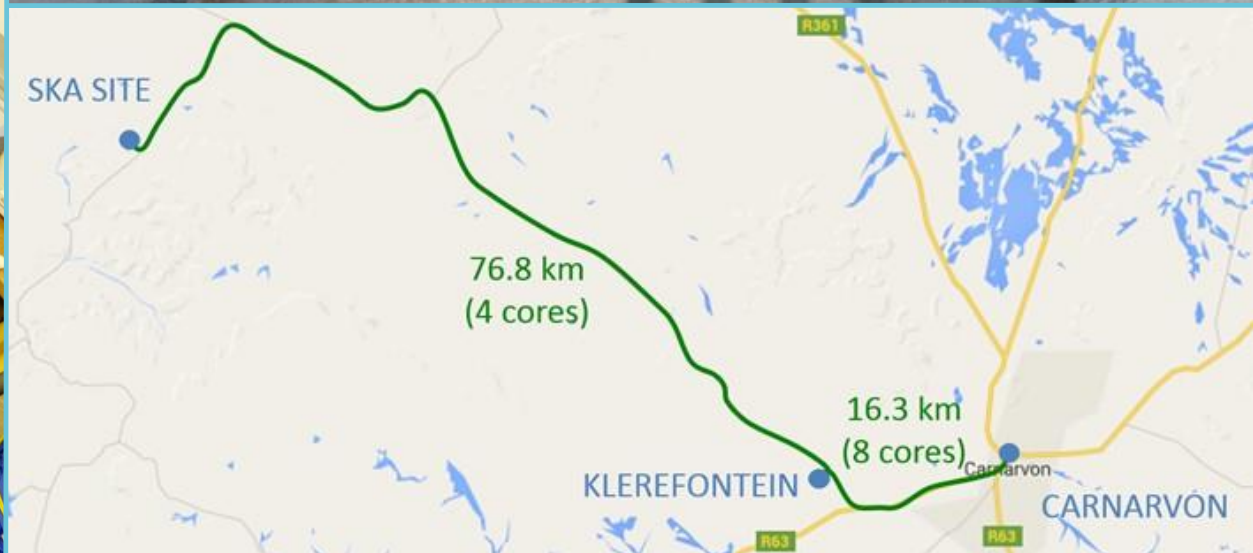
- Transmitted signal reflected back from remote site
- Self-heterodyned
- Actuator pre-compensates outgoing signal



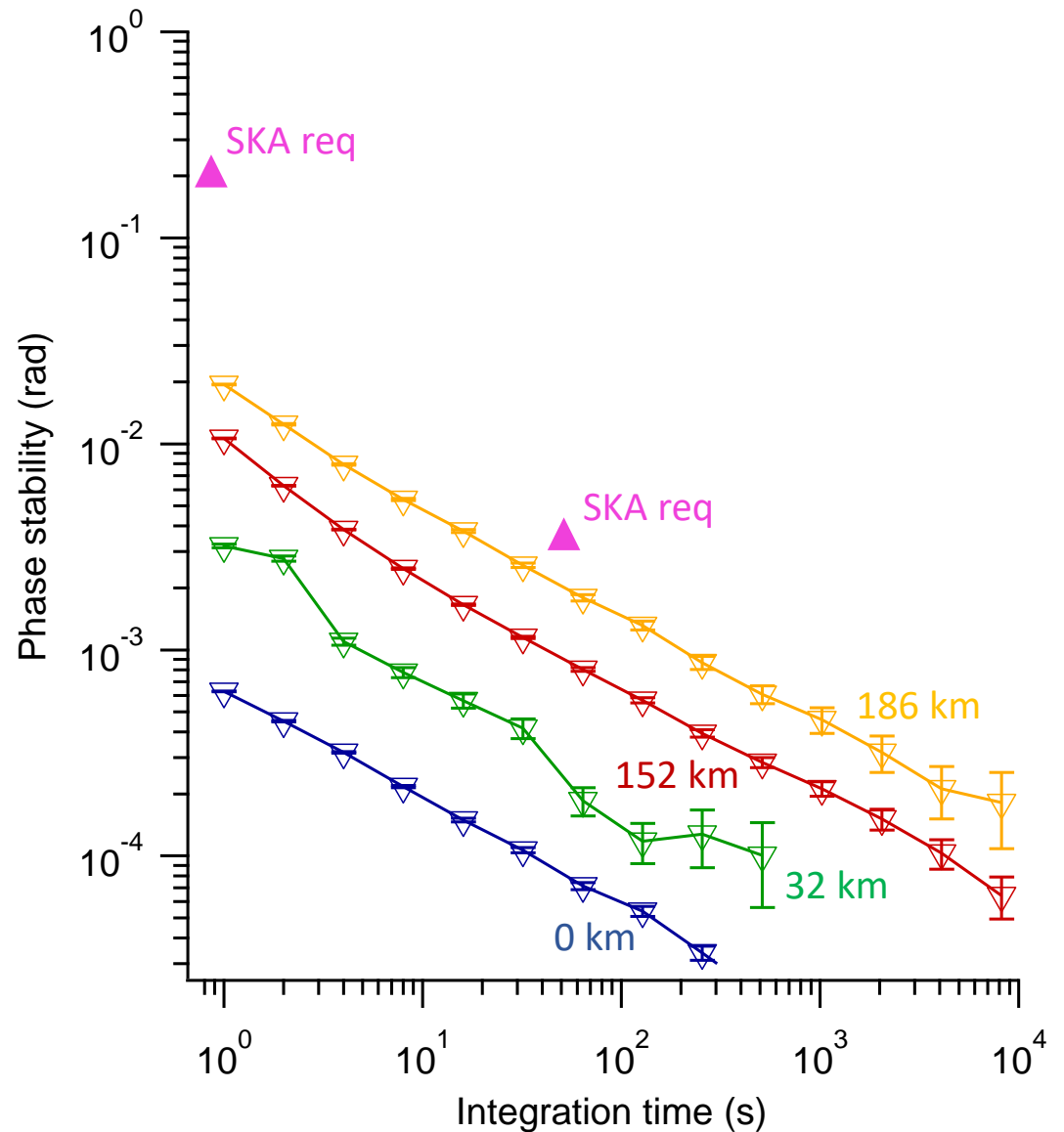
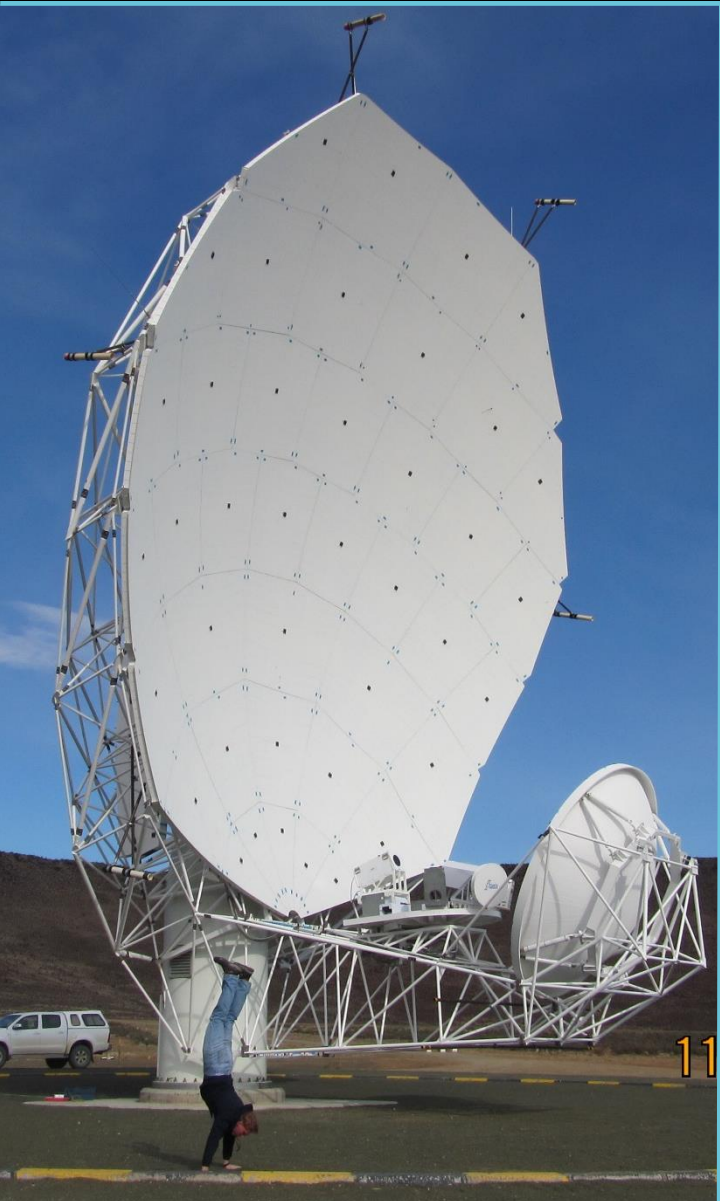
UWA SKA-Low



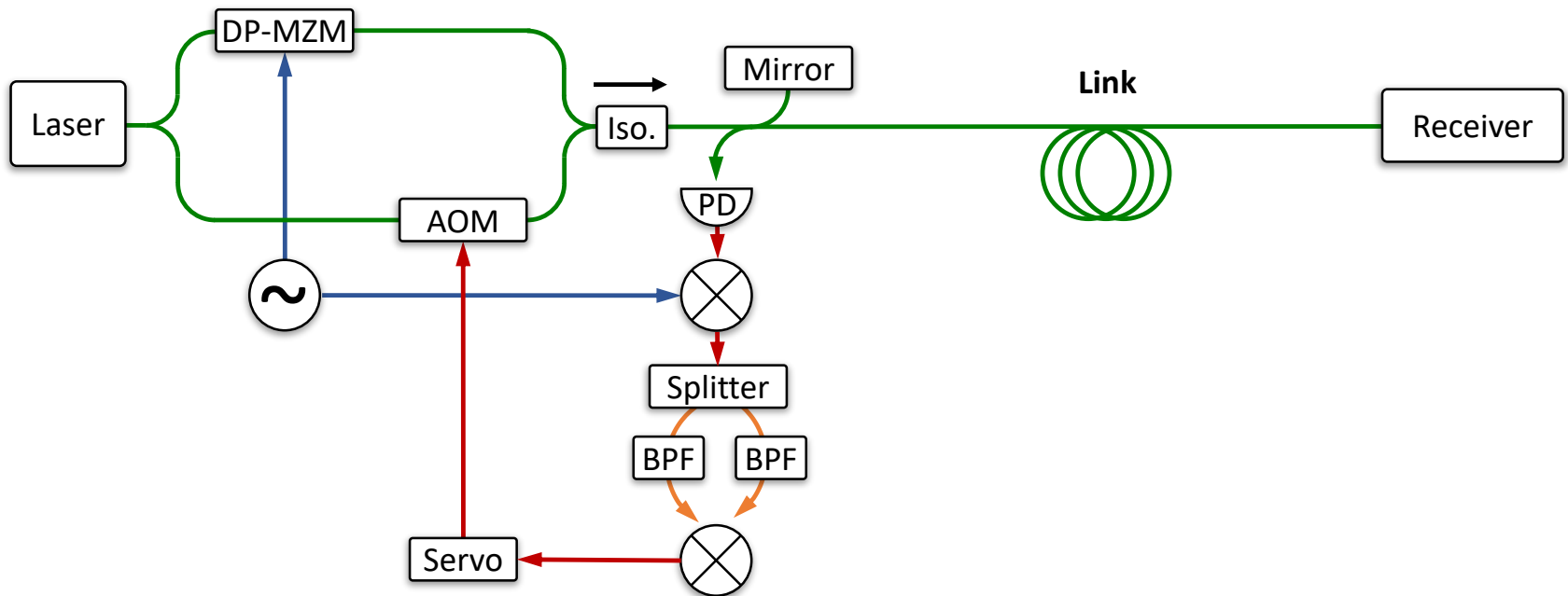
UWA SKA-low tests



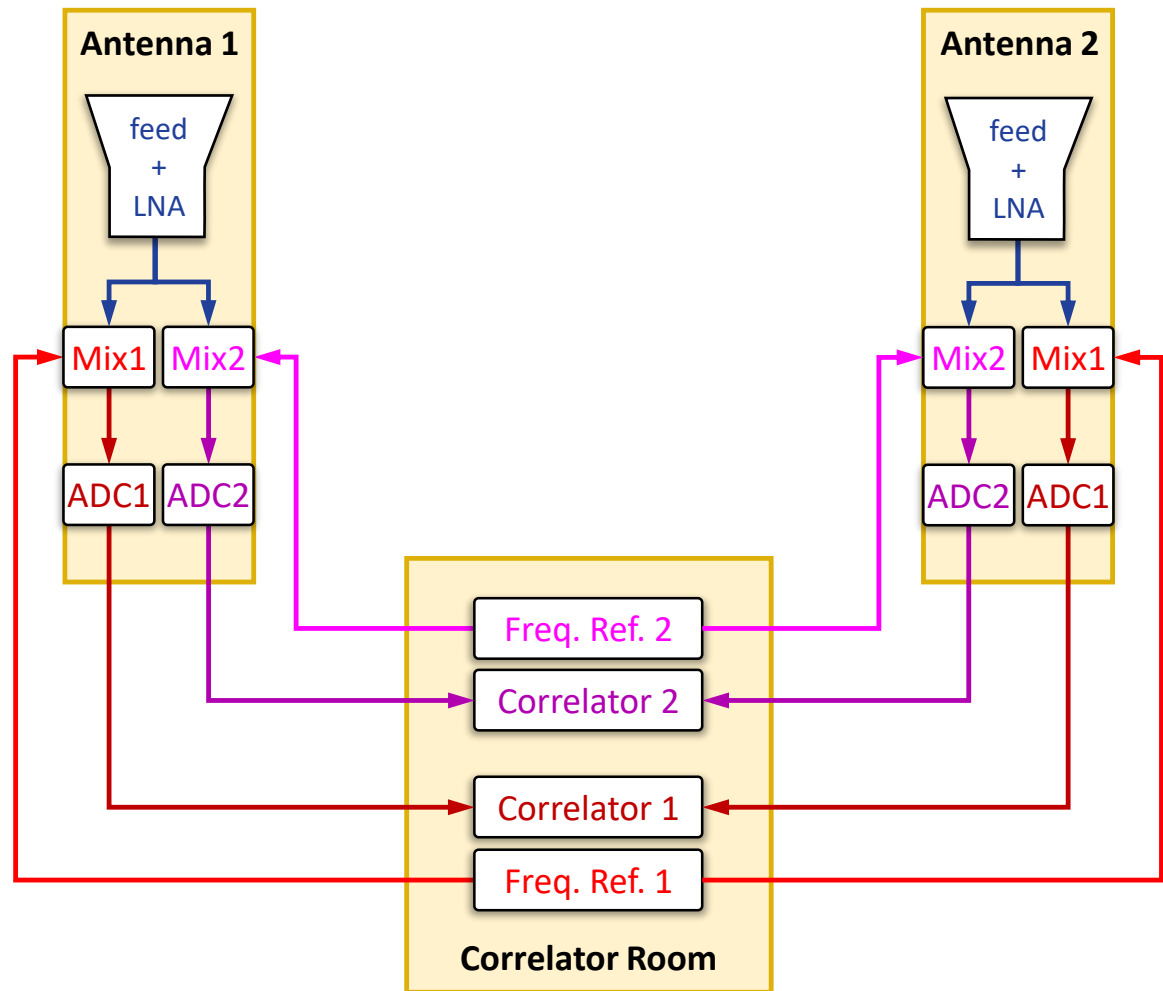
UWA SKA-low tests



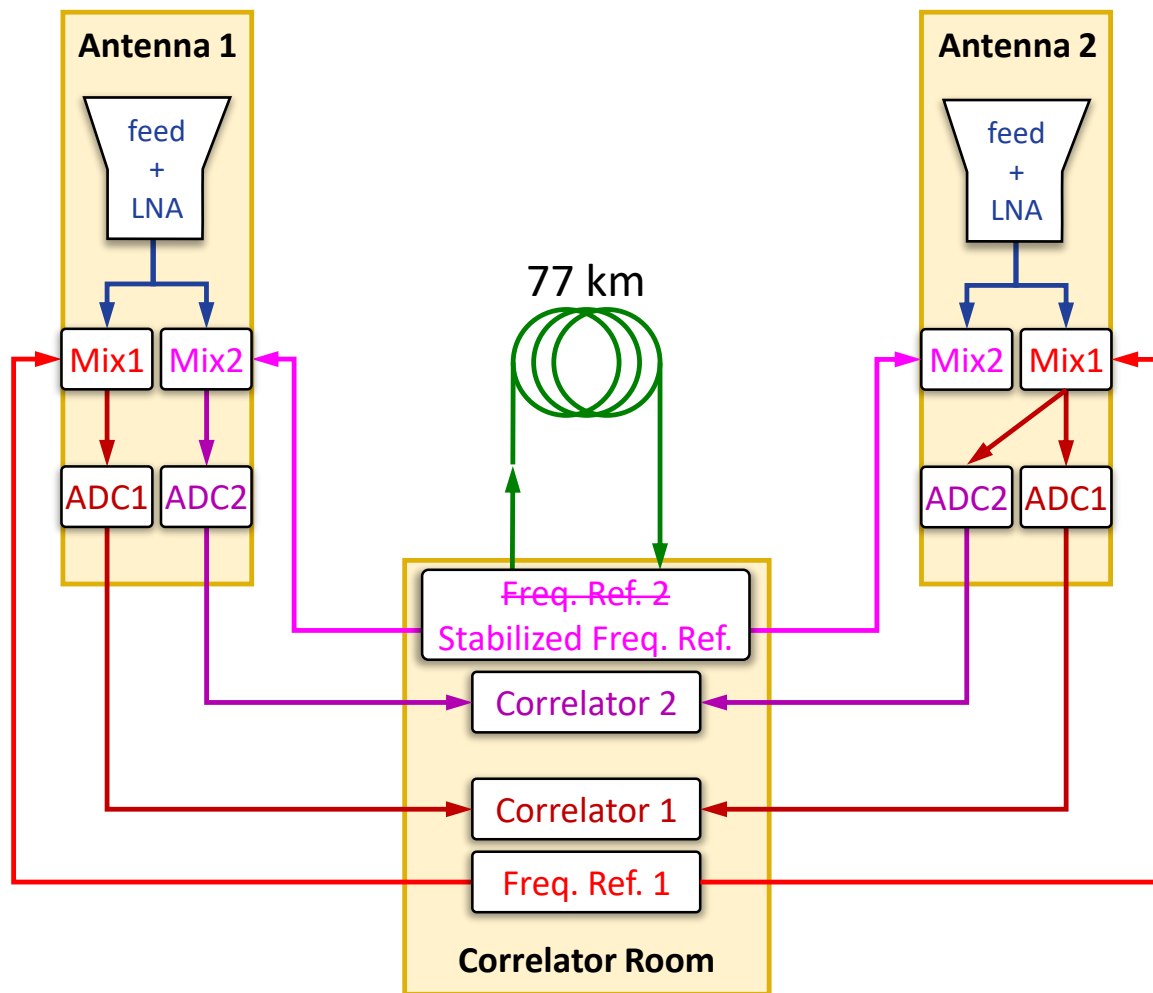
UWA SKA-Mid



ATCA Tests



ATCA Tests



ATCA Test Setup



ATCA Tests



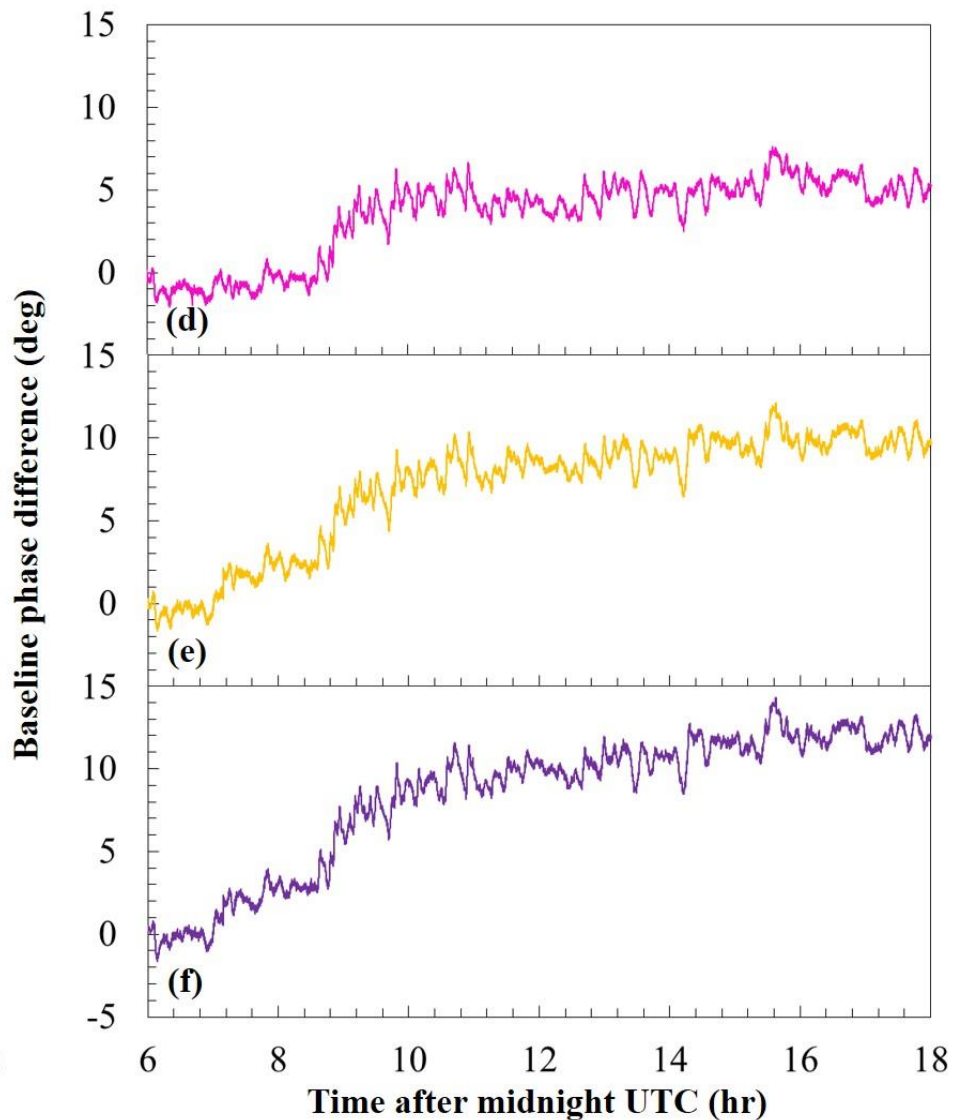
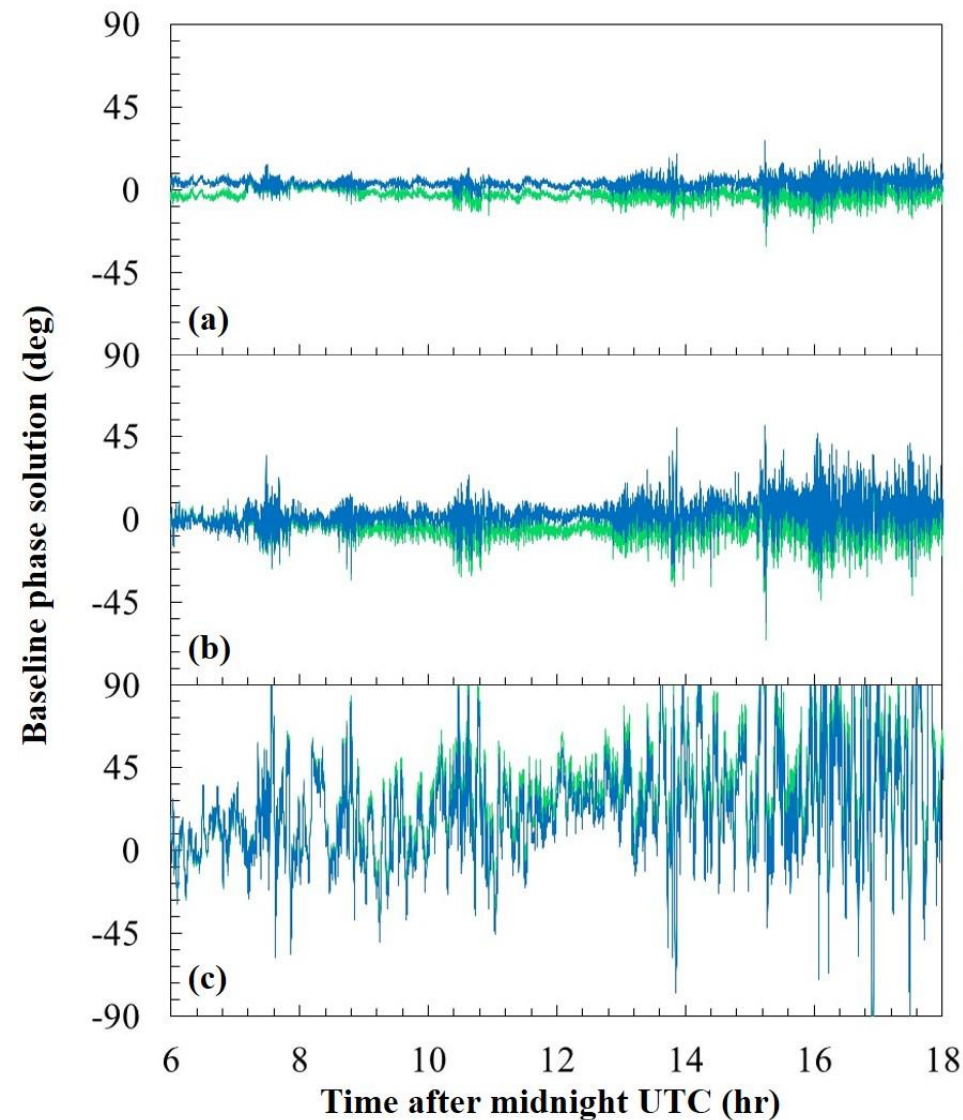
ATCA Tests



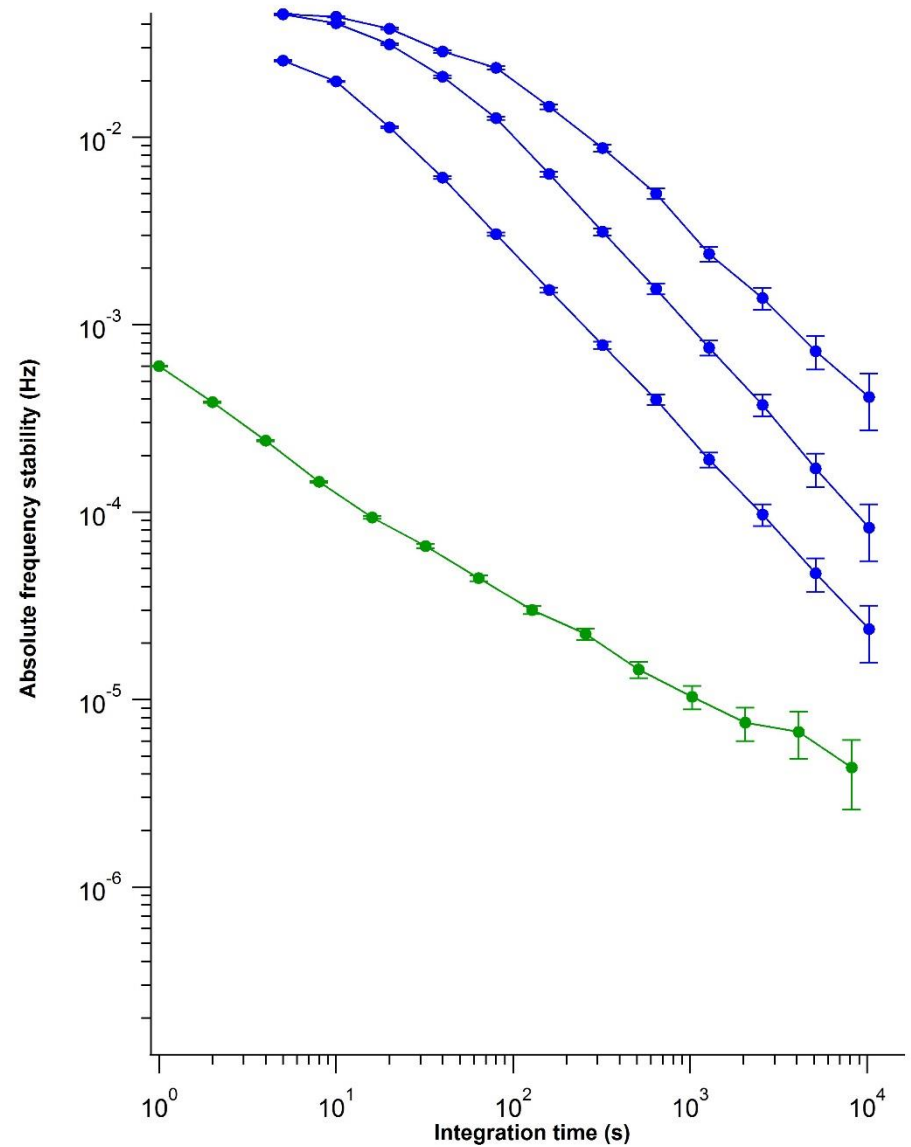
ATCA Tests



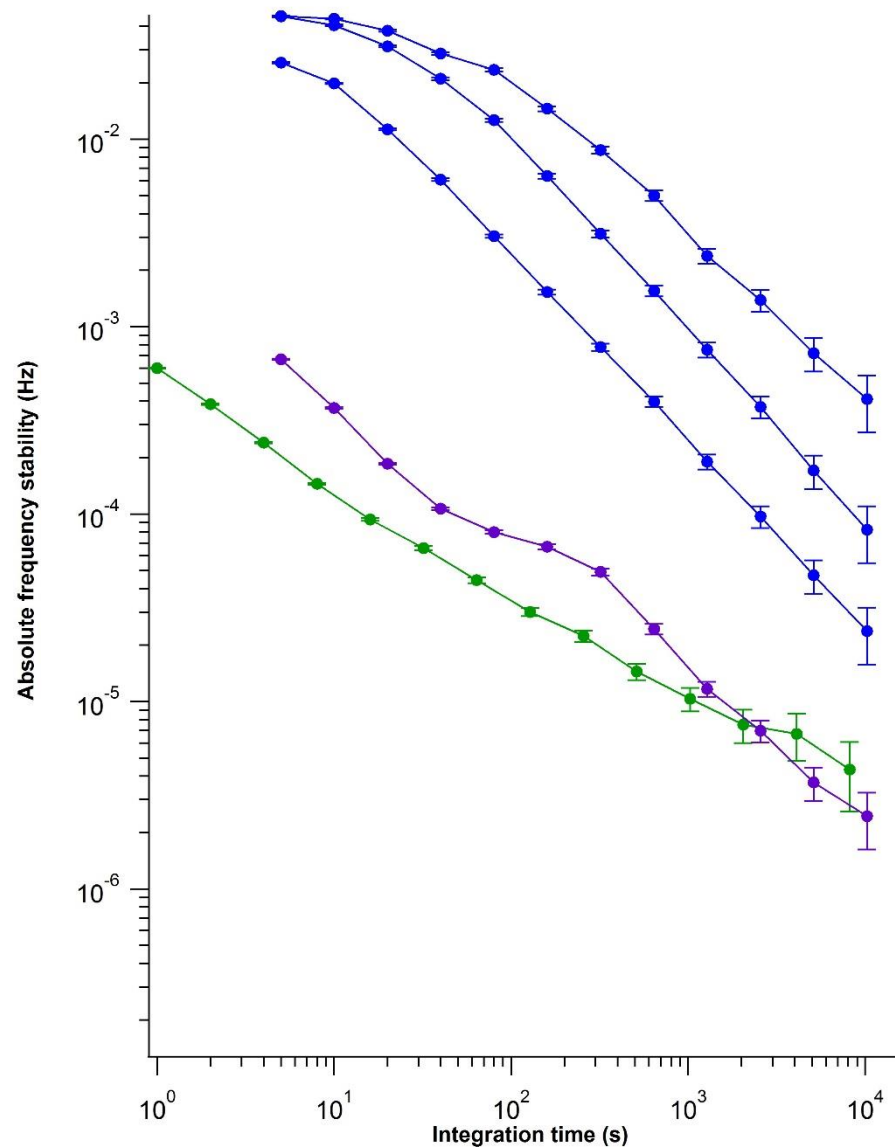
Analysis



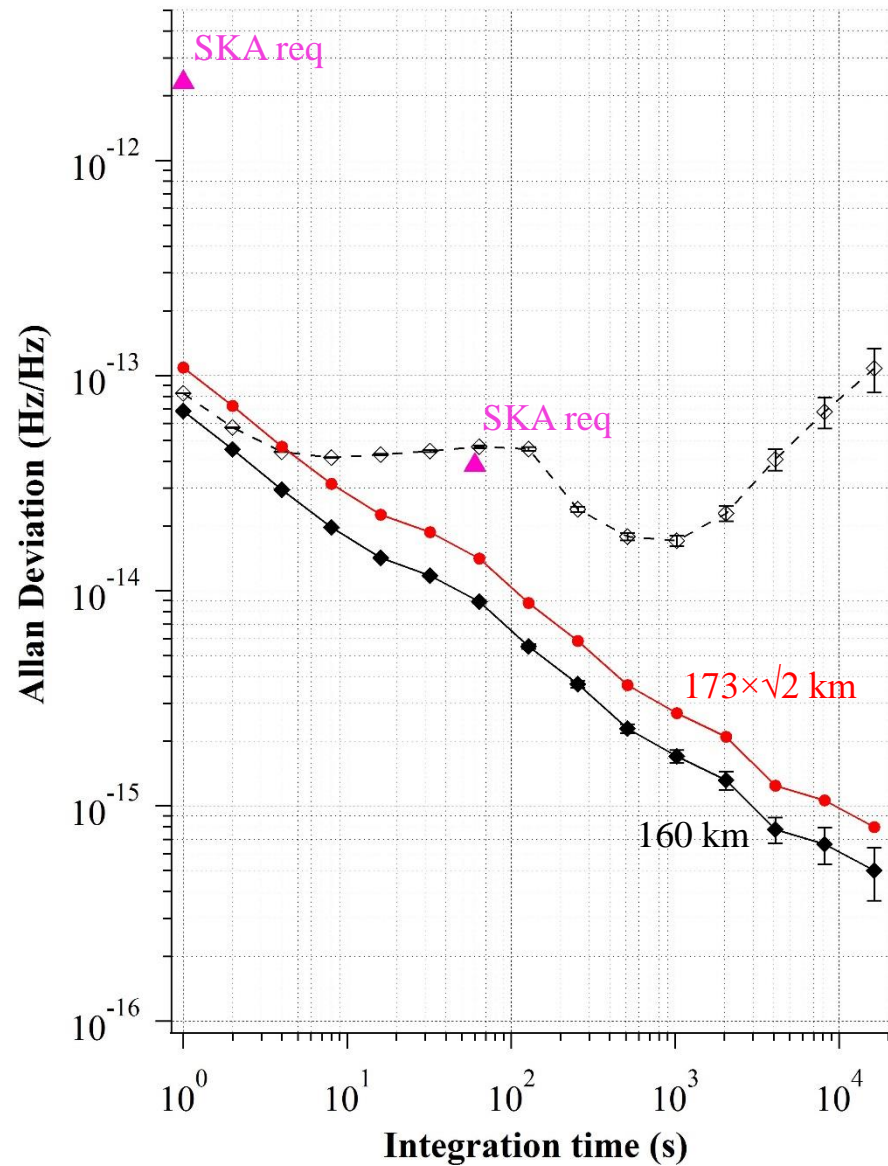
Analysis



Analysis

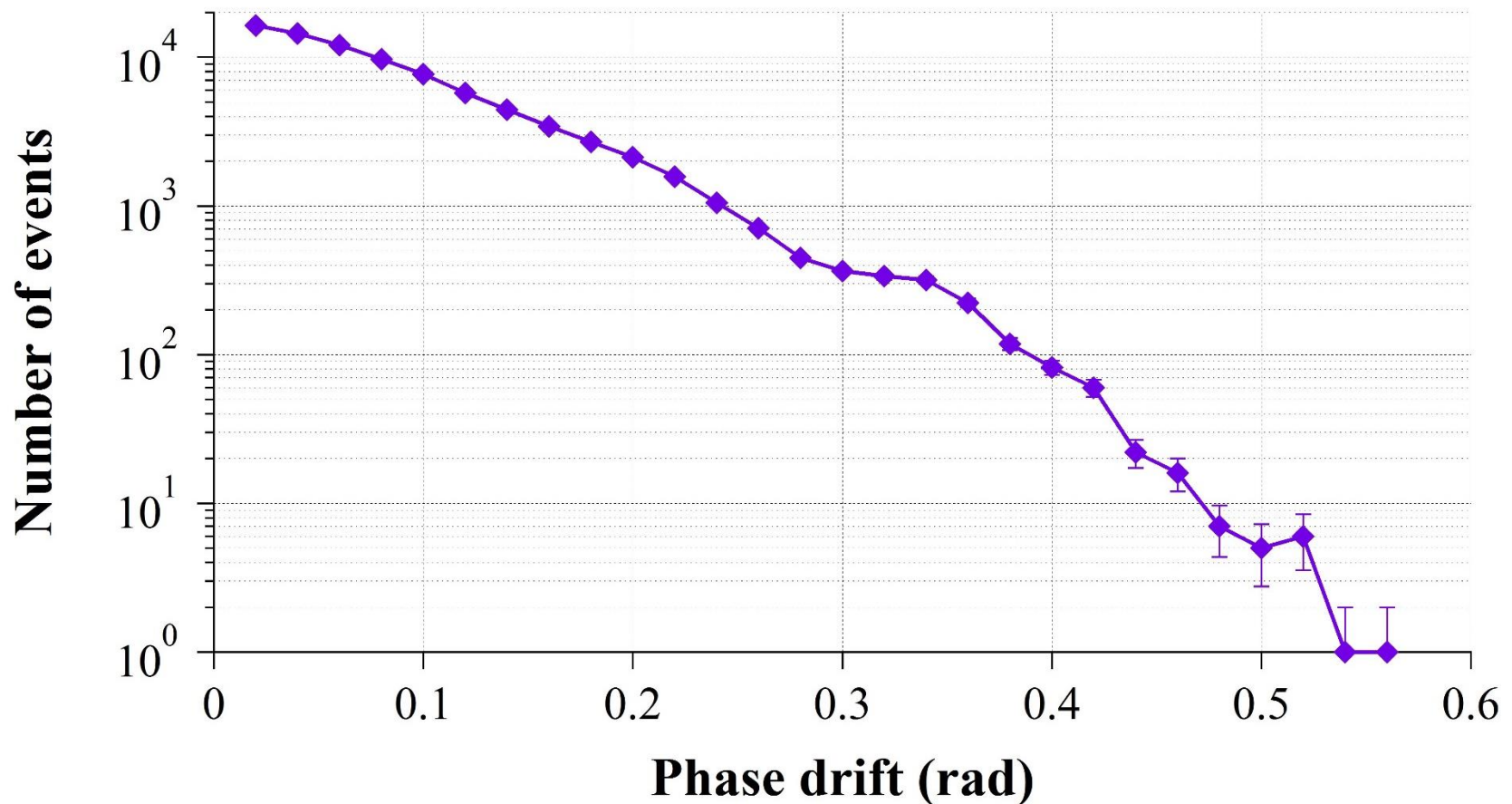


SKA requirements

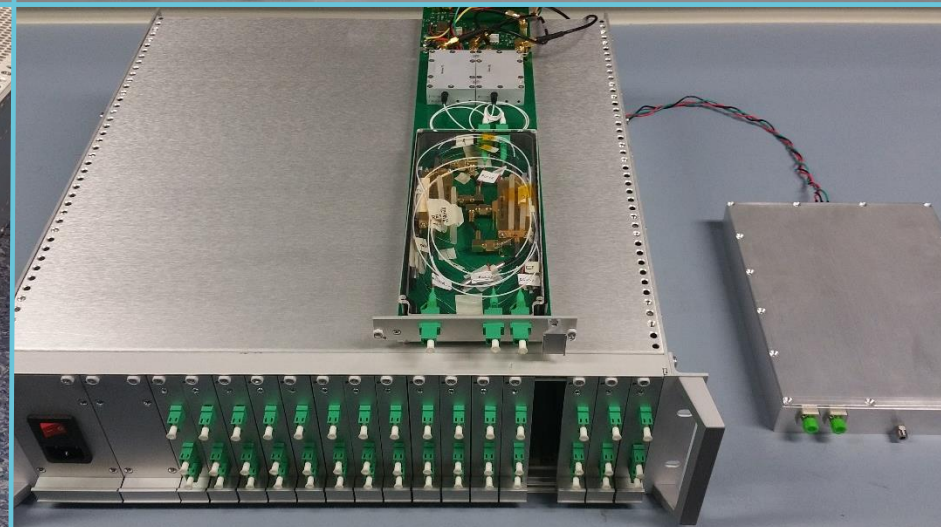
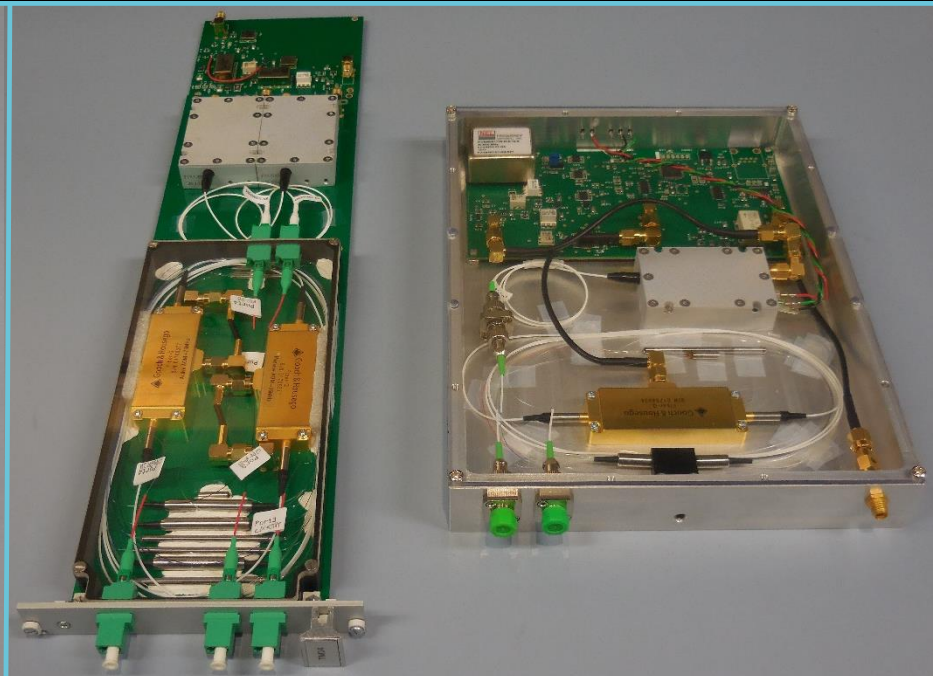
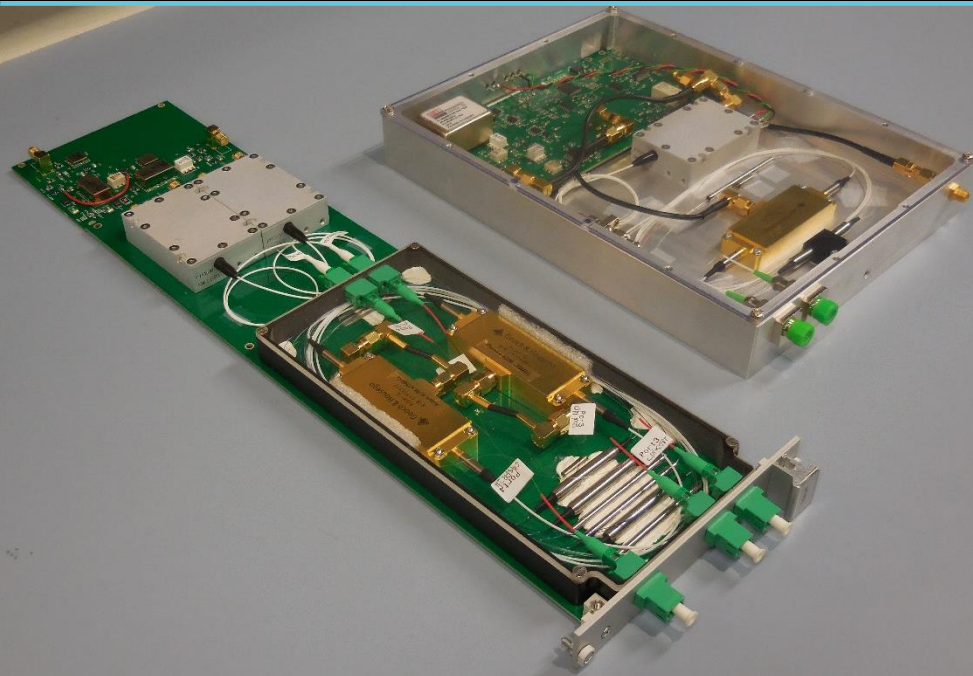


SKA requirements

- 600s phase drift < 1 rad
- 42hrs data, drifts < 0.08 rad (1 s.d.)



Design to Manufacture



Conclusions and future work

- UWA stabilized frequency transfer system meets SKA requirements under observing conditions
- Work progressing on design-to-manufacture
- Working towards AAVS1 and MeerKAT integration and end-to-end testing



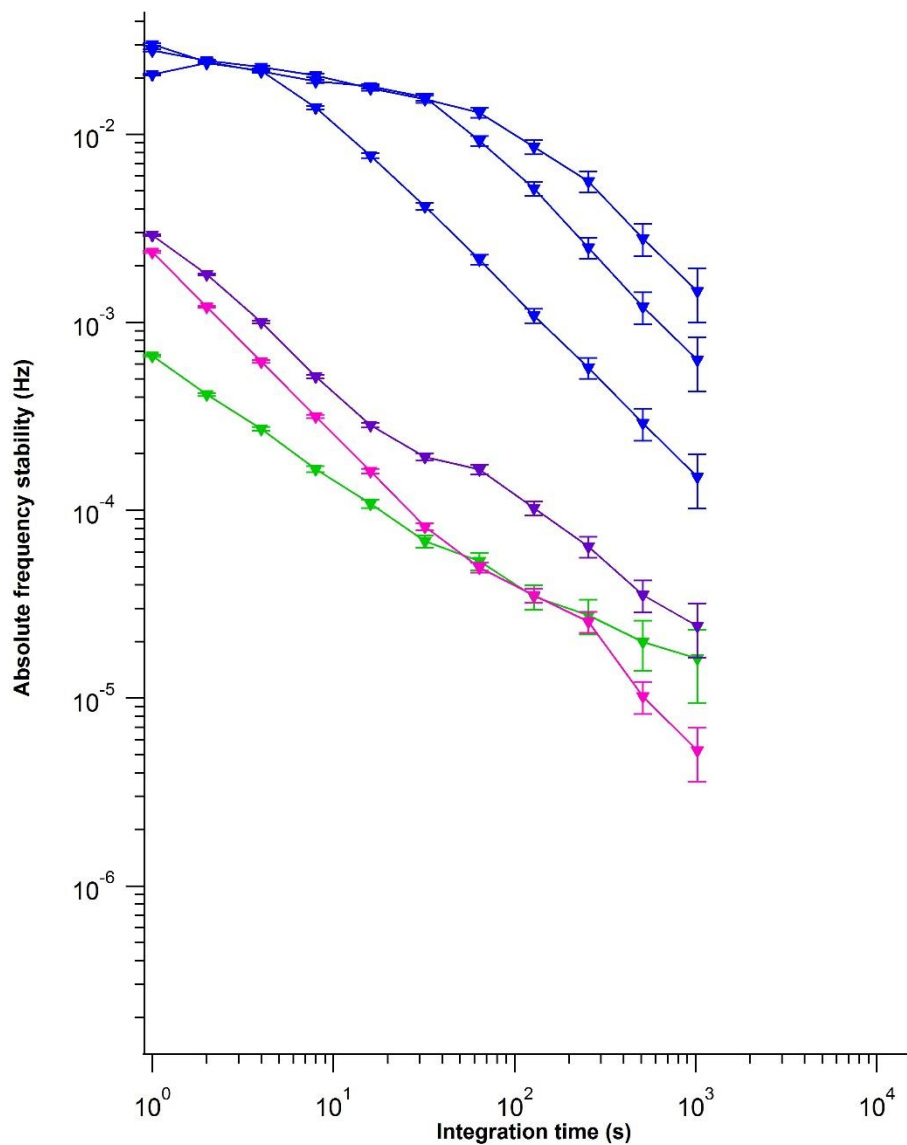
Acknowledgements

Many thanks for the hard work and effort of:

- Sascha Schediwy & Simon Stobie at UWA
- Richard Dodson and Maria Rioja at ICRAR
- Jamie Stevens, Mike Hill, Jock McFee, Peter Mirtschin & Brett Lennon at CASS

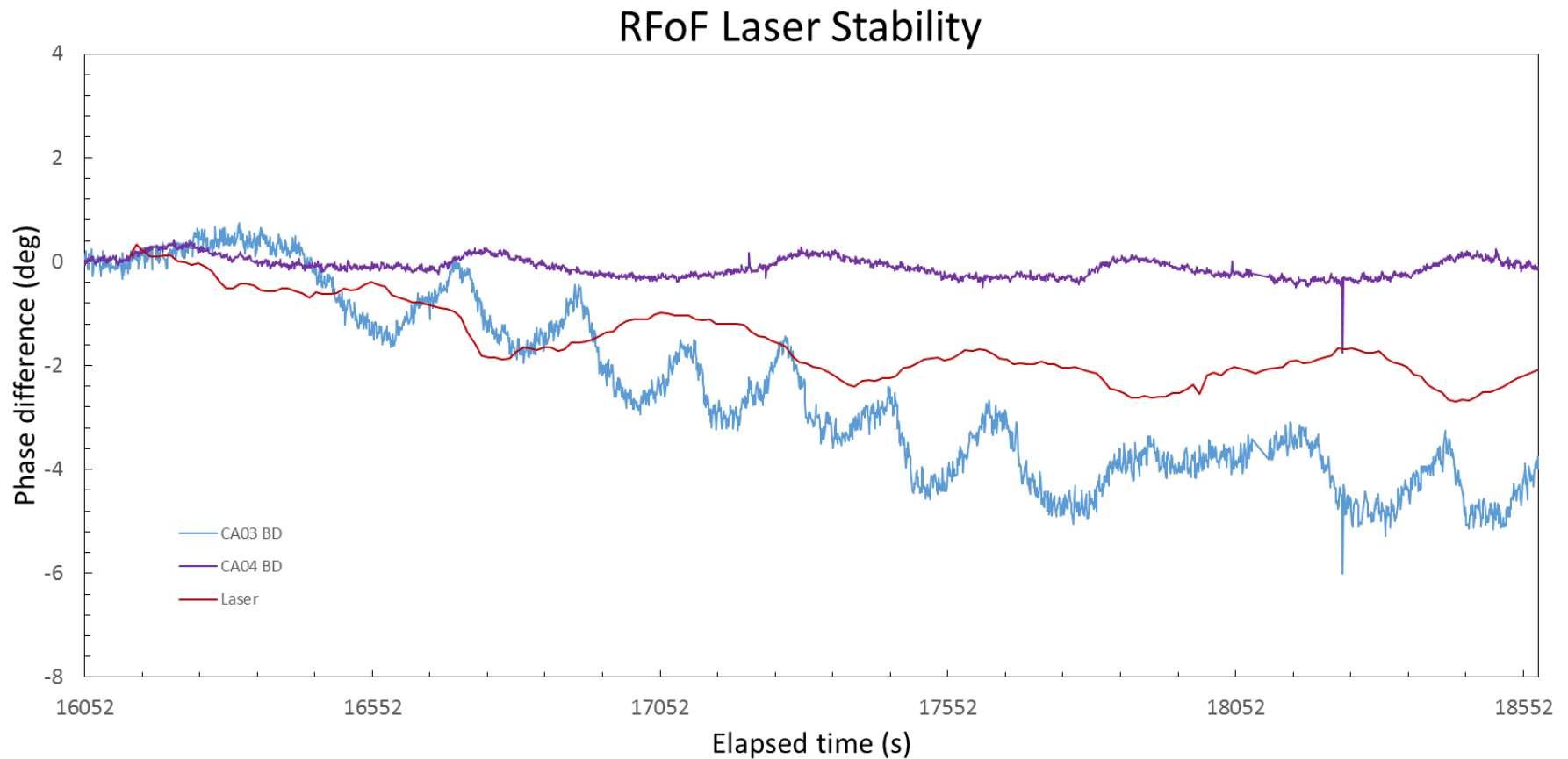
Extra Information

1-second logged data



Noise investigation

■ Non-coherent noise investigation - laser stability



Noise investigation

